Total Pages: 55

# HEADQUARTERS AERONAUTICAL SYSTEMS DIVISION AIR FORCE SYSTEMS COMMAND UNITED STATES AIR FORCE WRIGHT-PATTERSON AIR FORCE BASE, OHIO

Technical Memorandum ASNP-TM-61-28 24 November 1961 Directorate of Operational Support Engineering Deputy for Engineering Account: 921A

QUALIFICATION TESTING OF THE PACIFIC SCIENTIFIC COMPANY'S ALTITUDE SENSITIVE ACTUATORS, NOS. 1201117-0, 1201118-0 AND 1201119-0

#### I. PURPOSE

To evaluate the three different types of altitude sensitive actuators for possible use in an Air Force multi-stage parachute system.

#### II. FACTUAL DATA

#### 1. Test Items:

- a. Four altitude sensitive actuators, two each Part No. 121119-0 and one each Part No. 1201117-0 and 1201118-0, manufactured by the Pacific Scientific Company, were received from the Firewell Corporation, Buffalo, New York, on 18 October 1961 for qualification testing in accordance with the appropriate requirements as outlined in Item 2, Section II of this report.
- b. Two altitude sensitive indicators, one each Part No. 1201117-0 and 1201118-0 were subsequently received on 25 October 1961 after having been subjected to Items 4.1, 4.2, 4.5, 4.6 and 4.8.3 (of the requirements as outlined in Item 2, Section II of this report) by the Firewell Corporation.
- c. The actuators were designed to exert a force in excess of 100 pounds after a time delay of from 0.08 to 0.13 seconds after initiation. The various type actuators were precalibrated to fire at under 15,000 feet, under 16,500 feet and over 19,000 feet, respectively.
- 2. Test Requirements: The actuators were tested in accordance with requirements outlined in Appendix "K". These requirements are derived from the following Pacific Scientific Company Data Reports:
  - a. Numbers 655, 656 and 657 dated 4 October 1961.
  - b. Number 642 (as amended by conference of 19 September 1961).
- 3. Qualification Testing: A description of the testing appears in Appendix "B".

- 4. Test Results: The complete test results appear in Appendices "C", "D", "E", "F", "G" and "H".
- 5. Summary of Test Results: The test results are listed in Appendix "J".

#### III. CONCLUSIONS

- The subject actuators, as submitted, did not meet the test requirements.
- 2. The subject actuators did pass a portion of the required tests after being modified (reference Appendix "B") by the Pacific Scientific Company representative present.

#### IV. RECOMMENDATIONS

It is recommended that three new actuators, one each of the types tested, be resubmitted to substantiate that all discrepancies have been corrected.

PREPARED BY:

RONALD C. LINEBACK

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2LT, USAF

Publication Review

This report has been reviewed and is approved.

W. P. SHEPARDSON

Chief, Crew Equipment Division

Directorate of Operational Support

Engineering

#### APPENDIX A

#### DISTRIBUTION LIST (25)

Firewell Corporation (5) 3695 Broadway Avenue Buffalo, New York

Pacific Scientific Company (5) 10242 Placentia Avenue Anaheim, California

6511 Test Group (2) USNAS El Centro, California

ASNPSP-3 (12)

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#### APPENDIX B

#### QUALIFICATION TESTS

- 1. The qualification testing was carried out in four phases, as follows:
- a. Phase I. Two actuators, one each Type 1201117 and 1201118, were tested by the Firewell Corporation in accordance with paragraphs 4.1, 4.2, 4.5, 4.6 and 4.8.3 of the requirements referenced in Item 2, Section II of this report.
- b. Phase II. The above-described actuators were then tested by the Aeronautical Systems Division in accordance with paragraphs 4.8.4 and 4.8.5 of the referenced requirements.
- c. Phase III. Simultaneously with the above testing, one actuator (Type 1201118) was tested in accordance with paragraphs 4.7.2, 4.7.3, 4.8.6, 4.8.7 and 4.8.8 of the referenced requirements.
- c. Phase IV. Two actuators, Type 1201119, were concurrently tested with the above in accordance with paragraphs 4.3, 4.4, 4.7.2, 4.7.3, 4.7.4, 4.8.1 and 4.8.2 of the referenced requirements.
- 2. The following discrepancies were noted during the tests:
- a. Five of the six test samples could not be cocked after three to eight firings. These failures were considered by the Pacific Scientific representative to be due to scoring of the power spring guide assembly by the power spring (belleville washers). This fault was apparently corrected by hardening the guide assembly and tumbling the belleville washers to eliminate sharp edges. A life test of 75 firings was conducted successfully after the parts were changed.
- b. The reset tool (temporary cocking pin) consistently became prematurely disengaged. This was considered to be the result of improper tempering and configuration of the pin retaining spring and by the lack of an arming pin guide bushing. The first set of pins were not hardened and the retaining shoulder broke down. A second set of pins were supplied and these proved more usable although one of these broke during the cold temperature test.
- c. The test sample #201 would not fire after being armed and shocked at 16,500 feet and then being taken up to 26,000 feet. The unit was torn down and the head of a small hollow pin in the transfer shaft was found to be causing hang up when the aneroid tripped the release mechanism. This was corrected by use of a file and the shock and acceleration tests were then conducted successfully.

- d. The devices consistently fired within an altitude range of  $\pm$  500 feet at ambient conditions and within  $\pm$  1,000 feet at high and low temperature. However, it is to be noted that the calibration of the various devices was such as to allow firings to overlap or occur outside of the required 15,000 and 19,000 feet intervals.
- e. The timers on devices #204 and #205 proved to be adversely affected by exposure to cold temperature. The time delay varied from 0.28 to 0.41 seconds. (Requirement .08 to .13)
- f. The hollow pins retaining the arming levers to their respective shafts were found to fail with a force of from 10 to 12 pounds exerted on the lever. One pin failed (sheared) during test. It was understood that this pin is to be replaced by a solid 0.060 inch diameter pin.
- g. The leak indicators on four of the six devices became inoperative either as a result of unrestrained firing or from the shock tests. The manufacturer is understood to be correcting this fault by adding two more teeth to the follower sector of the altitude indicator.

#### APPENDIX C

#### ACCELERATION

Report No.

61-156-223

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Technical Memorandum ASNP-TM-61-28

# AERCHAUTICAL SYSTEMS DIVISION WRIGHT MORY DEMONSTRATE MIX DRY ISHOWXXX

WRIGHT-PATTERSON AIR FORCE BASE, OHIO

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(ASTEVD) ENVIRONMENTAL DIVISION DIRECTORATE OF ENGINEERING TEST AND ABORTORY

EVALUATION REPORT

# AUTOMATIC PARACHUTE AUTUATORS

REPORT NR: 61-156-223

DATE:

PROJECT NR: 5776

TYPE EVALUATION: Acceleration

MANUFACTURER: Pacific Scientific Co.

SPEC NR: BahiMit WCLSJ-1-23075

SUBMITTED BY: ASSPSP3 (Lt. Linebeck)

ITEM SERIAL NR: 120-1118

120-1117

Test Conducted: 31 Cct (1

# 1. PURPOSE:

To evaluate the operational response and the post test effects of sustained acceleration on two automatic parachete actuators.

### 2. FACTUAL DATA:

- a. The two devices submitted for testing are used in a multistage parachate operation. The design of both is nearly identical and differ substantially only in the altitude at which each unit is set to trigger.
- b. The actuator identified as the drogue deploy is adjusted to function at or above 19,000 feet ... The drogue release actuator is adjusted to trigger at 16,500 feet 2500 feet.
- o. For the acceleration test each device in turn was mounted on a suitable fixture and secured to the test platform of the instrument centrifuge. Buch actuator was subjected to 30 'g' of sustained acceleration for 1 minute, in the plus and mirms direction, along the three principal axes. Fig. 1 Appendix A of this report illustrates the direction of the applied 'g'.
- d. The drogue release was powered, and fired for each orientation, after one minute of acceleration. The drogue deploy was powered for each mounting position, socelerated for one minute, but not fired while on the centrifuge. The final step in the test procedure of the drogue deploy, consisted of placing the instrument in an altitude chamber and evacuating the latter to an equivalent of 19,000 feet, or until the actuator fired.

# 3. CONCLUSIONS:

The automatic parachute actuators submitted for seceleration testing,

nst Report Nr. ASTSVD-61-

successfully negotiated the requirements of the test procedure.

4.	HETELMAENDATIONS:

None. Data submitted for information	None.	Data	submitted	for	information
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PREPARED BY:

MCHARD C. McK MDM
Test Project Engineer

CONCURECED IN:

LUUID SCHAPFER
Colonel, USAF
Directorate of Engineering Test
Deputy for Test and Support

CONCURRED IN:

HICH S. LIPPMAN Rechnical Director Deporty for Test and Support

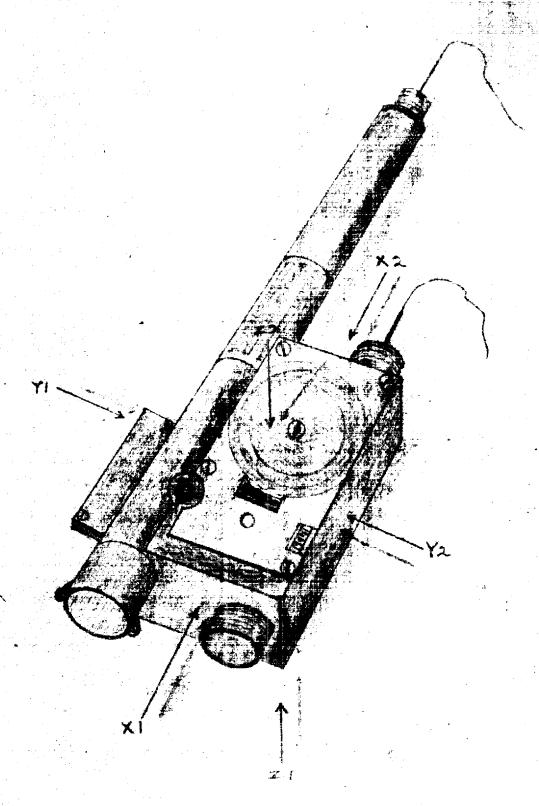
REPROVED BY:

Test Report Mr. ASTEVD-61-156-223

APPENDIX "A"

Figure 1 Automatic Parachute Actuators

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#### APPENDIX D

SHOCK

Report No.

61-156-222 (ASTEVD)

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# ARROMAUTICAL SYSTEMS DIVISION MRIGHT X MIRX OF YELLOW MENT X CONTER WRIGHT-PATTERSON AIR FORCE BASE, OHIO

DEFUTI FOR TEST AND SUPPORT

(ASTEVD) ENVIRONMENTAL DIVISION

DIRECTORATE OF LABORATORIES

DIRECTORATE OF ENGINEERING TEST LABORATORY

#### **EVALUATION REPORT**

#### AUTOMATIC PARACHUTE ACTUATORS

REPORT NR: 61-156-222 (ASTEVD)

DATE:

PROJECT NR: 5778

TYPE EVALUATION: Shock

MANUFACTURER:

Pacific-Scientific Co.

Data Report 642

SUBMITTED BY: ASNPSP-3 (Lt. Lineback)

ITEM SERIAL NR:

1201118 -203

1201118 -201

#### 1. PURPOSE:

To test two each parachute actuators submitted by the Firewell Corporation and manufactured by the Pacific-Scientific Company.

#### 2. FACTUAL DATA:

- This test was conducted on 26-27 Oct 1961.
- b. The parachute actuators are intended for a classified project.
- c. The testing was accomplished in accordance with Pacific-Scientific Data Report No. 642 dated 13 July 1961 amended 19 September 1961 and instructions from Project Engineer, Lt. Lineback.
- d. The equipment used to perform this test was a Jan-S-lili type shock machine with a plate spring having a spring constant of 1590 lbs/in installed in an altitude chamber.
  - e. Procedure for actuator 1201118 S/N 203:
- (1) With actuator S/N 203 loaded and arming pin inserted, the specimen was mounted on the shock machine to correspond with the direction of intended shock.
- (2) The altitude was then increased to 18,500 ft. (prescribed by project engineer, Lt. Lineback).
- (3) The arming pin was removed and the specimen was subjected to 30 g shock, while noting if release pulled the power cable during shock.
- (h) The altitude was then decreased to ambient pressure, noting and recording the altitude at which the release pulls the power cable.

Report Nr: 61-156-222 (ASTEVD)

- (5) Steps 1-4 were then repeated for the five remaining directions of shock. (6 directions total).
  - f. Procedures for actuator 1201118, S/N 201.
- (1) With actuator 3/N 201 loaded and arming pin removed, the specimen was mounted on the shock machine to correspond with the direction of intended shock.
- (2) The altitude was then increased to 16,500 ft (prescribed by project engineer).
- (3) The actuator was then subjected to 30 g shock, while noting if the release pulled power cable during shock.
- (4) The altitude was then increased at the rate of 100 ft/sec, noting and recording the altitude at which the release pulls the power cable.
  - (5) Steps 1-4 were then repeated for the five remaining directions of shock.
- g. Mr. George Goodrich and Mr. Verne Morgan of Pacific Scientific were present during the test to perform minor maintenance and repair on the actuators. Lt. Lineback of ASNPSP-3 was an observer of the test and made alterations in the test procedures as outlined in this report.

#### h. RESULTS -

The following chart indicates the shock altitude and release altitude:

RUN	UNIT NO.	POSITION	ARMING ALT.	SHOCK ALT.	RELEASE ALT.
1	S/N 203	longitudinal pin-down	20,500 ft	20,500 ft.	17,000 ft.
2	Ħ	<sup>#</sup> pin-up	18,500 '	18,500	17,000
3	Ħ	edgewise spring-up	18,500	18,500	16,900
4	Ħ	* spring-down	18,500	18,500	17,100
5	Ħ	Sideways face-up	18,500	18,500	17,500
6	44	" face-down	18,500	18,500	17,300
7	a∕N 201	longitudinal pin-up	station alt. =	16,500 to	
7.1	<b>es</b>	repeat 7	# #	16,500	19,600
8	H	pin down	<del>4</del> #	16,500 to	23,500 no release
8.1	**	repeat 8	et W	16,500	19,600
9	#	edgewise spring-up	4 9	16,500	19,500
10	Ħ	spring-down	# 6	16,500	19,500
11	<del></del>	sideways face-up	e #	16,500	19,400
12	Ħ	f face-down	ff #	16,500	19,900

After run 3 specimen S/N 203 was pulled for repairs due to lpading difficulties. The same symptum was encountered after runs 4 and 5, however, through some manipulation of the loading spring, the actuators were loaded.

After shock in run Number 7, the actuator failed to release even though the altiude was permitted to attain 26,500 ft. Scoring of the eneroid shaft was thought to be the cause of failure. Actuator S/N 201 was examined by Mr. Morgan and adjusted. After the correspinced to the correspinced to the correspinced to the correspinced to the chamber, however, difficulty was encountered in loading.

The actuators did not pull the power cables during the snocks. From information received from the project engineer, the release altitudes should be 10,500 ft for 1/N 201. The recorded release altitudes of these actuators when they operated properly were not within the limits of +500 ft. In the regaining of the actuators, the ameroic barometers were not recalibrated, therefore, the release sititude was altered. All release sititudes were within a 600 ft range hence the ameroid setting could have been changed to a setting within this 500 ft difference and the +500 ft limit could be met. The releases were to be checked for release altitude in an altitude chamber in Building h5. The data from these runs will be taken into consideration by the project engineer

#### 3. CONCLUSIONS:

Due to the amount of repair recaired on these sobustors during the test and from the information received from the project sugheser, it cannot be absolutely determined in shock caused the failure. It also appears that these items may be unreliable especially if product control is not rigid.

#### A. RECOMBENDATIONS:

It is recommended that these lies be completely retested under conditions of shock after they have been properly reversed.

Gronce A. HIRSCH Colonel, USAF Ass't Deputy for Test and Support

1.

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ANEROID CYCLING, OVERPRESSURE, TIMER ACCURACY, ANEROID ACCURACY, ANEROID HYSTERESIS, HIGH ALTITUDE - LCW TEMPERATURE AND HIGH TEMPERATURE

Report No.

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Technical Memorandum ASNP-TM-61-28

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WRIGHT-PATTERSON AIR FORCE BASE, OHIO

Revivonmental Division THE OFFICE PROPERTY OF THE PROPERTY OF THE

Test Directorate of Engineering

# **EVALUATION REPORT** Automatic Parachute Actuators

REPORT NR: ASTEVS-61-156-224

DATE:

PROJECT NR: 5778

MANUFACTURER: Facific Scientific Company

SUBMITTED BY: ASPESP-3

Major A. N. Abelson

TYPE EVALUATION: AMEROIG Cycling, Over-

or 5 (10) - 15

pressure. Timer Accuracy. Ameroid Accuracy. Ameroid Accuracy. Ameroid Hysteresis. High Albitude.

Exhibit Br: WOLSJ-1-23075 Item Park Mr: 120119-0 Item Ser Mrs: 204 and 205

1. FREESE: To obtain operational data on two automatic perashute estuators when subjected to various test conditions.

#### FACTUAL DATA

- The aginators are designed to pull the ripcord of a parachate after a time delay of between .08 and .13 seconds provided they are within a pressure altitude of 15,000 ± 500 feet at normal ambient and 15,000 ± 1,000 feet at low or high temperature (-65°F or 160°F).
- b. Testing of the sotustors was accomplished in accordance with a suborder submitted by Major A. N. Abelson, ASNPSP-3, dated 3 October 1961. This suborder outlimed the testing procedures in accordance with a Pacific-Scientific Report Nr. 642. amended by a Memorandum for Record dated 12 September 1961. Additional operational eritoria for these tests were furnished by Lt. R. C. Lineback, And SP-3. Each testing procedure covered by this report will contain the appropriate beeding and respective paragraph number referenced in Report Mr. 642.
- 4. Operational testing of the actuators was started on 19 October 1961 and test acaptated on 2 November 1961. During this time the actuators were subjected to the following tests in the order listed; Amerold Accuracy, Timer Accuracy, Amerold Hysteresis, Ameroid Cycling, Overpressure, High Altitude-Low Temperature, and High Temperature. Operational discrepancies noted during these tests were as follows. During the aperoid accuracy test the aperoid leak indicator on each actuator became defective resulting in inaccurate altitude indications at simulated altitude conditions It was noted during the test phases through the aperoid cycling that the power cable apring latching mechanism became difficult to engage necessitating the replacement of the power spring guide cylinder on each actuator. After the overpressure test the anaroid release point on actuator ar. 204 was below the operational requirement. Testing at low temperature found the anerold release point on actuator ar. 204 to be below the operational requirement. The timer mechanism on each actuator at low

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Lagrenture operated above the operational requirements. It high temperature the eneroid release point on actuator or. 265 and above the operational requirement. It was also noted throughout all these tests that the actuator eraing oins and poor retention when inserted into the eraing stot. This measurable direquent pin replacement and retention spring adjustment.

- d. Upon completion of testing the actuators were returned to bt. R. C. Theo ex. A complete description of all tests is presented in a auromolo, ical order as appendix A of this report.
- J. Confliction: The automatic parachute actuators used in this test failed to satisfy all the operational requirements of this test.
- 4. And the state of the recommended that the statement be considered uncovingence; for service use under the conditions imposed during this test.

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LATE COVER SYE

GEORGE A. KIRSCH

Colonel, USAF

Ass't Deputy for Test and Support

- 1. neroid accuracy (fars. 4.1.7). Lies actuator was subjected to a simulated altitude of 20,000 feet and the armid, his was alled. The test chamber altitude who lowered at a rate of 1% feet per second and each inseroid release point was noted. Letutor or. 30% operated at 1.,500 feet and intustor or. 30% operated at 1.,500 feet and intustor or. 30% operated at 1.,500 feet. But a partitions were within the operational requirement of 1.,000 feet. It was noted furing this test phase that the ameroid leav indicator on each indicator had account defective and was indicating below the sea level range when the actuators were at station pressure. This caused the indicators to indicate inaccurately at simulated altitude conditions. He further checks were made of takes indicators during the reservoice operational tests.
- 2. Timer Accuracy (Para. 4.7.2). Bix timer operational checks were assess on even actuator. The time delay, after publing the arming pin, varied between .10 and .12 seconds for each Accuracy. These timer operations were within the operational requirements of between .00 and .13 seconds.
- j. meroid hysteresis (here, 4.7.4). The actuators were subjected to a simulated altitude of 30,000 feet and each actuator armine pin was pulled. The test chamber altitude was lowered at a rate of 200 feet per second and each ameroid release point was noted. Actuator are 204 operated at 14,900 feet and actuator are 205 operated at 15,000 feet. Both operations were within the operational requirement of 15,000 feet.
- 4. Ineroid Cycling (Para. 4.5). Both actuators were subjected to continuously varying altitude cycles of room temperature (+75°F) from station pressure to 35.000 feet and return to station pressure. This constituted one complete cycle and 1000 such cycles were imposed on each actuator. Spon completion of the 1000 cycles an aneroid accuracy check was made on each actuator. Sith an altitude descent rate of 120 feet per second, actuator nr. 204 operated at 15.000 feet and actuator nr. 205 operated at 15.000 feet. South actuators contract within the operational requirement of 15.000±500 feet. It was noted up to this time that throughout the first four test phases that the actuator power cable spring latching mechanism became difficult to engage. Corrective action was taken by the minurecturer's representative Ar. V. Morgan by replacing the power spring guide cylinder on each actuator.
- D. Overpressure (1018. 4.4). The actuators were subjected to an absolute pressure of 30 inches ag for a period of one hour. Open completion of the one hour overpressure the actuators were returned to stmospheric pressure and subjected to this condition for a period of 72 hours. In aneroid accuracy check was then conducted on each actuator. Actuator ar. 204 operated at 14.400 feet and actuator ar. 205 operated at 15.400 feet. Actuator ar. 205 operated within the operational requirement of 15.000 5500 feet but accustor ar. 204 was below.
- 6. High Altitude Low Temperature (Para. 4.0.1). Soon actuators were subjected to an ambient temperature of -650 Per and a simulated altitude of 50.000 Peet for a period of four hours. Upon completion of these four hours the actuators were subjected to an unbient temperature of -650 Per at station resoure for an additional period of four hours. Upon completion of this exposure, and while still at -650 Per an aneroid four hours, and timer accuracy check was made on each actuator. The aneroid on estuator are 204 operated at 13.750 feet and the time delay on four timer operations were 34.

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.41, .j2, and .2d seconds. The energia on actuator mr. 20j operates at 1,,650 feet and one sime delay on four timer operations were .j4, .1, .j9, and .jd seconds. The chartest of actuator mr. 20j was within the operational requirement of 1,,500 feet but the aneroid on actuator mr. 204 did not fulfill this requirement. The timer operation on both actuators was in excess of one lime delay requirement of hetween .00 and .ly seconds.

7. Algh Temperature (res. 4.6.7). The octustors were subjected to an ambient temperature of 160°7% a set a period of 19 nours. Upon completion of this exposing, and waite still at that temperature, an eneroid accuracy and timer accuracy a eck was made at each actuator. The interpolation of this exposing the aneroid on actuator no. The operated at 15,100 feet. Three timer accuracy, enochs were made on each actuator who all time delays being recorded at between all and all seconds. The aneroid operation of actuator no. 20% was within the operational retain mans of 15,000 floor but its interpol on actuator no. 20% did not fulfull this requirement. The timer operation of both actuators was within the operational requirement of actuator. We timer operation of security was conducted.

#### APPENDIX F

# SALT FOG, SAND AND DUST. AND HUMIDITY

Report No.

Page

ASTEVS-61-155-217, 218, 219

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# ARONAUTICAL SYSTEMS DIVISION

WRIGHT-PATTERSON AIR FORCE BASE, OHIO

ASTEVS/MPO/ ja

Environmental Division

Directorate of Engineering

Test

# EVALUATION REPORT Automatic Parachute Actuator. 1 Ea.

REPORT NR:

ASTEVS-61-155-217. 218. 219

DATE:

PROJECT NR. 5778

MANUFACTURER: Pacific-Scientific Co.

SPEC NR:

TYPE EVALUATION: Salt Fog. Sand & Dust.

Humidity Deta Report 642

SUBMITTED BY: ASMPSP-3

Major A. M. Abelson

Park Nrs

202

1201118-0

1. FURPOSE: To determine the resistance of the actuator to salt fog, sand and dust, and humidity test conditions.

#### 2. PACTUAL DATA:

- a. The actuator is a device which is intended to release a parachute ripcord rautomatically at a preset altitude.
- b. The release was tested in accordance with the applicable paragraphs of Specification NiL-E-5272 as stipulated in Data Report 642 as changed by conference held on 19 September 1961.
  - . The test schedule was as follows:
- (1) The salt fog test was conducted in test facility ar. 45-7 for 50 hours starting on 23 October 1961 and terminating 25 October 1961.
- (2) The sand and dust test was conducted in test facility nr. 45-6 for 12 hours sterting 25 October 1961 and terminating 26 October 1961.
- (3) The humidity test was conducted in test facility nr. 45-4 for one 24 hour ayele from 26 October 1961 to 27 October 1961 after which the test item was moved to a humidity chember in Building 22 where four additional cycles were completed from 30 October 1961 to 3 November 1961. The total exposure time was 120 hours.
- d. During exposure to environmental test conditions the actuator was inside a parachute pack as required by the applicable specifications.
- e. At the end of the salt fog test, the exterior of the actuator housing was free of visible salt fog condensate; however, rust on internal components was considered to be evidence that some salt fog had entered the case. When the actuator was operated in altitude facility nr. 45-11, it pulled the ripsord cable at 16.500

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feet which was satisfactory. Difficulty was experienced in resetting the release or the next test; however, this condition was found to be due to faulty manufacture Inot to the environmental test conditions. The manufacturer's representative, who was summoned by the project engineer, examined a prototype release which had the same defect in the recetting mechanism. The representative claimed to have determined the proper corrective action to be taken.

- f. At the end of the send and dust exposure period, the actuator was removed from the paracaute pack and found to be externally and internally free of sand and dust. when the actuator was tested in altitude facility nr. 45-11, it bulled the ripcord cable properly at 16,700 feet and was considered to be satisfactory.
- g. It the end of the numidity exposure period the octuator was removed from the parachute pass. It was found to be covered with moisture both internally and externally. Gust that started in the preceding salt fog test was advanced. Photograph wr. 61-4651. posudix "" of this report illustrates the extent of the rust. The actuator was subjected to a functional test in the stratosphere chamber in Building 22. The first ettempt to tringer the actuator was unsuccessful because the maing pin was restrained by excessive friction. The actuator was then repositioned so that it could be triggered by means of the side lever. The actuator pulled the ripcord cable at 10,000 feet and was considered to be satisfactory. xamination of the ording jin disclosed that the friction was due to rust.
- h. Lt. Linebuck, a representative of the project engineer, participated in the functional tests following exposure to the environmental conditions.

#### i. <u>Thathanlung</u>

- 8. If the exception of the rust and the difficulty with the reset mechanism, as referenced above, the actuator is considered to love withstood the selt for test conditions to which it was exposed.
- b. The actuator is considered to have withstood the sand and dust test conditions to which it was exposed.
- c. Due to the presence of moisture inside the case of the actuator and the rust as referenced above, the actuator is not considered to have withstood the municity test conditions to which it was exposed.
- 4. and a same is said to be in recommended that:
- a. The actuator be considered resistant to galt for as represented by the above described test, provided the components that rusted are adequately protected.
- b. The actuator be considered resistant to sand and dust as represented by the above described sand and dust test.
- c. The actuator be considered nonresistant to humidity as represented by the above described humility test.
  - d. The case of the actuator be improved to exclude hunidity from the interior.
- e. The resetting mechanism of the release be modified as necessary to eliminate the Ticulty referenced in paragraph 20.

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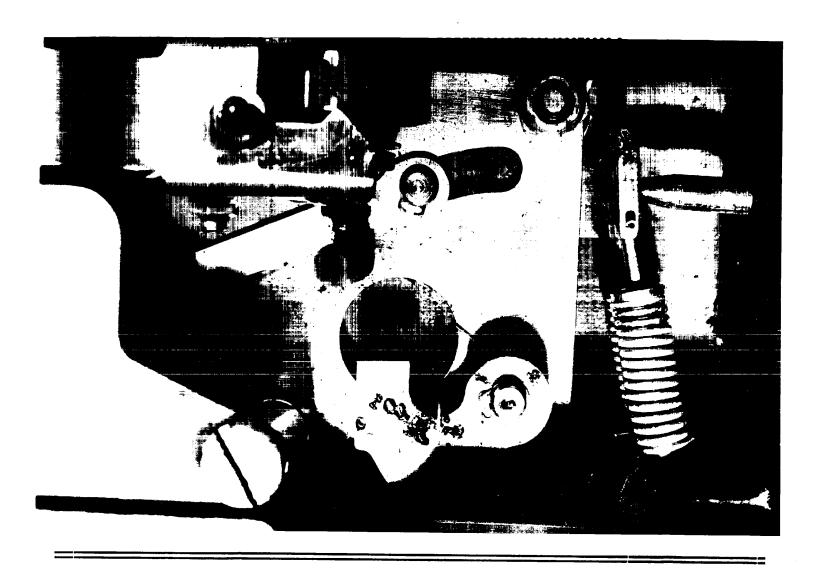
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LICHOTOL BY:

GEORGE A. KIRSCH

Colonel, USAF Ass't Deputy Comdr/Test and Support



AUTOMATIC PARACHUTE ACTUATOR AFTER SALT FOG TEST NR. 61-155-219

ASD ASTDP

DATE: 3 NOV 61 NEG. NR. 61-4031

#### APPENDIX G

# QUALIFICATION TESTS PERFORMED ON PACIFIC SCIENTIFIC CORP. PARACHUTE ACTUATOR NUMBER 1201117-0

<u>Report</u>

Firewel Report dtd 2 Nov 1961

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BUFFALO 25, N. Y.

November 2nd, 1961

QUALIFICATION TESTS PERFORMED ON PACIFIC SCIENTIFIC CORP. PARACHUTE ACTUATOR NUMBER 1201117-0

by The Firewel Company, Buffalo, N. Y.

Prepared by:

James K. Seitler Design Engineer

Approved by:

Alfred C. Barmasse

Project Engineer

Robert F. Zumwalt Director of Research Subsidiary of the Ara Equipment Corporation

3695 BROADWAY

BUFFALO 25, N. Y.

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Approved For Release 2003/03/10: CIA-RDP75B00285R000400070002-9

3695 BROADWAY BUFFALO 25, N. Y.

#### 1. PURPOSE:

Perform the portion of the qualification testing of the Pacific Scientific Corporation Parachute Actuator Number 1201117-0 assigned to the Firewel Company.

#### 2. REFERENCE SPECIFICATION:

Pacific Scientific Corporation

Number 655 -- Qualification Test Procedure for Drogue Deploy Actuator

Number 1201117-0

WADC Exhibit WCLSJ-1-23075, Appendix A, dated November 26th, 1957

ASD Document Data Report 642 as changed by Conference of September 19th. 1961.

#### 3. QUANTITY OF TEST ARTICLES:

One each -- Drogue Deploy Actuator Number 1201117-0 Serial Number 201

#### L. TEST PROCEDURE:

Paragraphs 4.1, 4.2, 4.5, 4.6 and 4.8.3 of ASD Document Data Report No. 642 as changed by the Conference of September 19th, 1961 were performed by the Firewel Company. Numbers in parenthesis refer to the referenced document.

### 4.1 Examination of Product (4.1):

4.1.1 The specimen examined conformed to the applicable drawing except that the guide bushing for the arming pin had not been assembled into the unit.

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BUFFALO 25, N. Y.

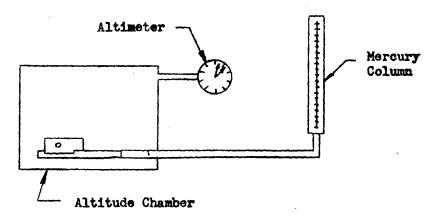
### 4.2 Venting Test (4.2):

#### 4.2.1 Test Procedure:

With the arming pin removed, the actuator was placed in an altitude chamber. A rubber tube was placed over the cable guide and connected to a mercury column.

The altitude was raised to 25,000 feet and then lowered at a rate between 150-250 FPS. The difference in the mercury column and altitude chamber readings should not exceed 100 feet. This test was performed twice.

#### 4.2.2 Test Setup:



#### 4.2.3 Test Results:

ALTITUDE CHAMBER READINGS	Hg COLUMN (1 100 FEET)
25,000 feet	OK
20,000 feet	OK
15,000 feet	OK
10,000 feet	OK
0 feet	OK OK

#### 4.2.4 Remarks:

The actuator performed satisfactorily.

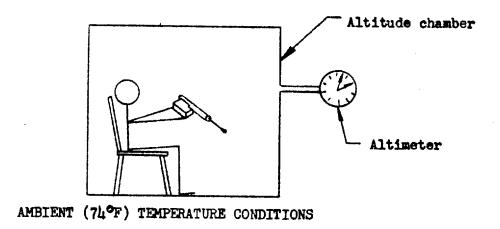
BUFFALO 25, N. Y.

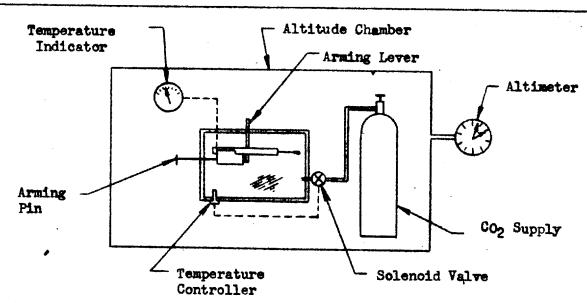
# 4.3 Timer Starting Life Test (4.5):

# 4.3.1 Test Procedure:

With the power spring NOT loaded, the power gear train was started by extracting the arming pin 300 times at room temperature. The same starting operation was conducted an additional 200 times, between -60° and -65°F. Because of the ameroid block on this unit, the tests were conducted in an altitude chamber at an altitude of 21,000/22,000 feet.

#### 4.3.2 Test Setup:





-60/-65°F TEMPERATURE CONDITIONS

FORM EDF 106

BUFFALO 25, N. Y.

#### 4.3.3 Test Results:

TEST CONDITIONS	Test	remarks
Ambient Test	300 cycles	OK
-60°/-65°F Test	200 cycles	OK

#### 4.3.4 Remarks:

After 110 actuations, the arming pin began to fail. This was caused because the pins had not been properly heat treated. New pins corrected the situation. The arming pin hole in the body casting showed signs of wear. This was due to the fact that the units were supplied without bushings as noted in paragraph 4.1. The 200 cycles cold test was performed by arming the unit at 18,000 feet, raising the chamber to 21,000 feet to set the mechanism and then firing for 30 cycles. The remaining 170 cycles were performed at 21,000 feet. The actuator operated satisfactorily.

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# 4.4 Power Actuation and Life Test (4.6):

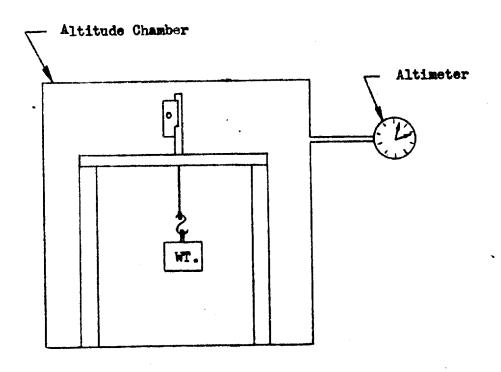
helial Test Procedure:

The actuator was loaded, mounted in a test fixture and operated fifty times with a 30-pound weight attached to the swaged fitting on the power cable.

The test was repeated 25 times with a 100-pound weight. The 100-pound weight was lifted at least two inches each time.

Because of the aneroid block on this unit, the tests were conducted in an altitude chamber at 21,000 feet at room temperature 74°F. The actuator was loaded each time with the resetting tool No. 1201138.

#### 4.4.2 Test Setup:



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# 4.4.3 Test Results:

Test	LOAD	REMARKS
50-cycle	30 pounds	ok
25-cycle	100 lbs - 2" lift	ok

# 4.4.4 Remarks:

Actuator operated satisfactorily.

BUFFALO 25, N. Y.

# 4.5 Vibration (4.8.3):

# 4.5.1 Test Procedure:

The actuator, cocked and with the arming pin inserted was subjected to linear vertical vibration for thirty minutes in each of three mutually perpendicular planes on a vibration stand. When mounted in the horizontal plane, the actuator was mounted upside down. In one of the positions the actuator was mounted so that the pawl for the reel actuator had the additional force of gravity tending to trip it. During this period of vibration, the frequency was varied continuously from 10 to 55 CPS with a double amplitude (total excursion) of 0.030 inch. The actuator should not operate the power cable during this period of vibration.

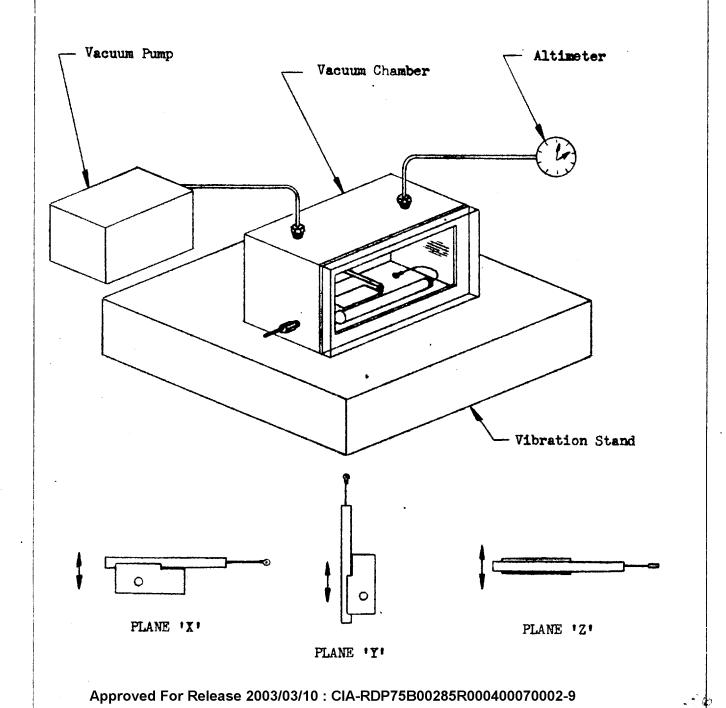
The actuator was then placed in an altitude chamber at a pressure simulating 18,500 feet. It was then vibrated for thirty minutes in each plane. Upon completion of the vibration in each plane, the altitude was raised to clear the actuator. The altitude was then reduced and the release was armed to ascertain the limits of firing.

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4.5.2 Test Setup:



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# 4.5.3 Test Results:

4.5.3.1 Ambient:

PLANE OF VIBRATION	VIBRATION CYCLE	REMARKS	
X Y Z	30 minutes 30 minutes 30 minutes	No fire No fire No fire	OK OK

4.5.3.2 Altitude:

	4.7.3.E A.	TOTOMOG!			
PLANE OF VIBRATION	VIBRATION CYCLE	ALT. CLEARED	ALT. RAISED	ALT. ARMED	REMARKS
X	30 minutes at 18,500 10-55 CPS	19,950 19,925 19,930 19,950	22,000 22,000 22,000 22,000 22,000	20,000 19,800 19,800 19,700 19,600	No fire - raised alt. to 20,400 - fired Fired - OK Fired - OK Fired - OK Mo Fire - OK
. <b>Z</b>	30 minutes at 18,500 10-55 CPS	19,950 19,950	22,000 22,000 22,000	20,000 19,800 19,700	No fire - raised alt. to 20,550 - fired Fired - OK Fired - OK
Y	30 minutes at 18,500 10-55 CPS	20,200 20,100 20,500 20,050 19,300 19,850 19,500	22,000 24,000 24,000 24,000 24,000 22,000 22,000 22,000	20,500 19,800 20,000 21,000 19,800 19,700 19,600 19,500	No fire - raised alt. to 23,000 - no fire No fire No fire Fired - OK Fired - OK Fired - OK No fire - OK

# 4.5.4 Remarks:

The results obtained immediately after vibration showed that the altitudes at which the mechanism fired were somewhat higher than normal operation, but still within specification. The only exception was that which appeared after vibrating in the 'Y' axis. Subsequent actuations were satisfactory.

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#### APPENDIX H

# QUALIFICATION TESTS PERFORMED ON PACIFIC SCIENTIFIC PARACHUTE ACTUATOR NUMBER 1201118-0

Report

Firewel Report
dtd 3 Nov 1961

QUALIFICATION TESTS PERFORMED ON PACIFIC SCIENTIFIC PARACHUTE ACTUATOR Number 1201118-0

By The Firewel Company, Buffalo, NY

Prepared by:

James K. Seitler Design Engineer

Approved by:

lired C. Barmasse Project Engineer

Director of Research

Approved For Release 2003/03/10: CIA-RDP75B00285R000400070002-9

BUFFALO 25, N. Y

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Subsidiary of the Aro Equipment Corporation

3695 BROADWAY

BUFFALO 25, N. Y.

#### 1. PURPOSE:

Perform the portion of the qualification testing of the Pacific Scientific Corporation parachute actuator Number 1201118-0 assigned to the Firewel Company.

# 2. REFERENCE SPECIFICATION:

Pacific Scientific Corporation:
Number 657 -- Qualification Test Procedure for Drogue Deploy Actuator
Number 1201118-0.

WADC Exhibit WCLSJ-1-23075, Appendix 'A', dated November 26th, 1957

ASD Document Data Report 642 as changed by Conference of September 19th 1961.

3. QUANTITY OF TEST ARTICLES:

One each -- Drogue deploy actuator Number 1201118-0, Serial Number 203

4. TEST PROCEDURE:

Paragraphs 4.1, 4.2, 4.5, 4.6 and 4.8.3 of ASD Document Data Report No. 642 as changed by the Conference of September 19th, 1961 were performed by the Firewel Company. Numbers in parenthesis refer to the referenced document.

# 4.1 Examination of Product - (4.1):

4.1.1 The specimen examined conformed to the applicable drawing except that the guide bushing for the arming pin had not been assembled into the unit.

BUFFALO 25, N. Y.

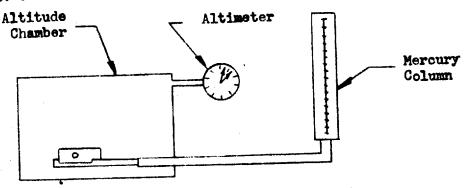
# 4.2 Venting Test (4.2):

# 4.2.1 Test Procedure:

With the arming pin removed, the actuator was placed in an altitude chamber. A rubber tube was placed over the cable guide and connected to a mercury column.

The altitude was raised to 25,000 feet and then lowered at a rate between 150-250 FPS. The difference in the mercury column and altitude chamber readings should not exceed 100 feet. This test was performed twice.

# 4.2.2 Test Setup:



# 4.2.3 Test Results:

ALTITUDE CHAMBER READINGS	Hg COLUMN (* 100 FEET)
25,000 feet 20,000 feet 15,000 feet 10,000 feet 0	OK OK OK OK

# 4.2.4 Remarks:

The actuator performed satisfactorily

Well THE FREWEL CO., INC.

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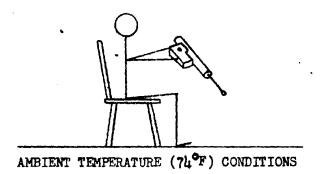
BUFFALO 25, N. Y.

# 4.3 Timer Starting Life Test (4.5):

#### 4.3.1 Test Procedure:

With the power spring  $\frac{NOT}{NOT}$  loaded, the power gear train was started by extracting the arming pin 300 times at room temperature. The same starting operation was conducted an additional 200 times, between -60° and -65°F.

# 4.3.2 Test Setup:



Temperature

Indicator

Arming

Lever

CO2 Supply

Temperature

Controller

Solenoid Valve

-60/-65°F CONDITIONS

BUFFALO 25, N. Y.

# 4.3.3 Test Results:

TEST CONDITIONS	TEST	REMARKS
Ambient test	300 cycles	OK
-600/-65 <sup>oF</sup> test	200 cycles	OK

# 4.3.4 Remarks:

The arming pin hole in the body casting showed signs of wear. This was due to the fact that the units were supplied without bushings as noted in paragraph 4.1.

BUFFALO 25, N. Y.

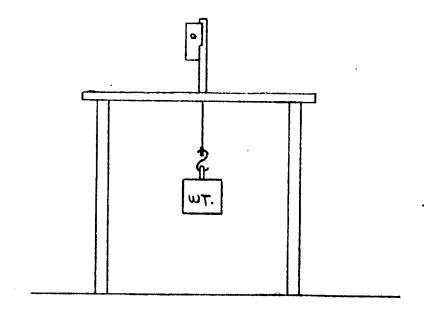
# 4.4 Power Actuation and Life Test (4.6):

# 4.4.1 Test Procedure:

The actuator was loaded, mounted in a test fixture and operated fifty times with a 30-pound weight attached to the swaged fitting on the power cable. The test was repeated 25 times with a 100-pound weight. The 100-pound weight was lifted at least two inches each time.

The actuator was loaded each time with the resetting tool Number 1201138.

4.4.2 Test Setup:



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4.4.3 Test Results:

TEST	LOAD	REMARKS
50 cycle	30 pounds	OK
25 cycle	100 lbs - 2" lift	OK

# 4.4.4 Remarks:

Actuator operated satisfactorily.

BUFFALO 25, N. Y.

# 4.5 <u>Vibration (4.8.3)</u>:

# 4.5.1 Test Procedure:

The actuator, cocked and with the arming pin inserted was subjected to linear vertical vibration for thirty minutes in each of three mutually perpendicular planes on a vibration stand. When mounted in a horizontal plane, the actuator was mounted upside down. In one of the positions, the actuator was mounted so that the pawl for the reel actuator, had the additional force of gravity tending to trip it. During this period of vibration, the frequency was varied continuously from 10 to 55 CPS with a double amplitude (total excursion) of 0.030 inch. The actuator should not operate the power cable during this period of vibration.

The actuator was then placed in an altitude chamber at a pressure simulating 17,800 feet. It was then vibrated for thirty minutes in each plane. Upon completion of the vibration in each plane, the altitude was reduced after the release was armed to ascertain the limits of firing.

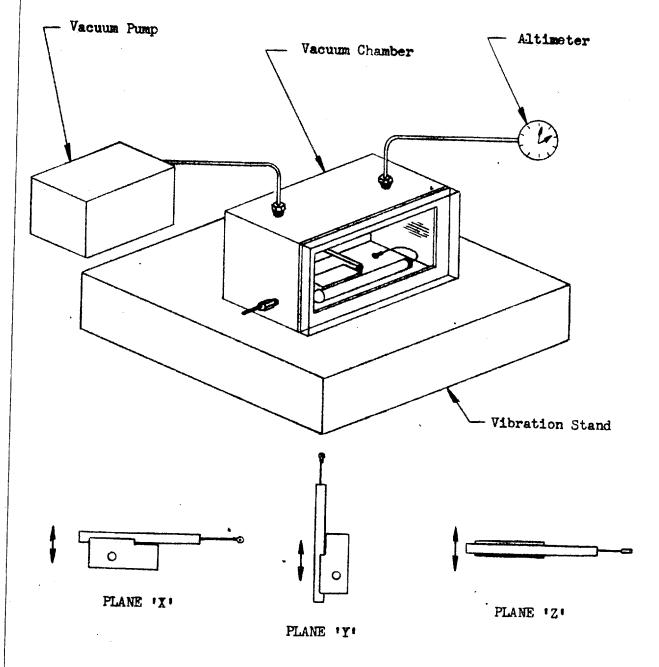
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BUFFALO 25, N. Y.

4.5.2 Test Setup:



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BUFFALO 25, N. Y.

# 4.5.3 Test Results:

4.5.3.1 Ambient:

PLANE OF VIBRATION	REMARKS	
X	30 minutes	No fire - OK
Y	30 minutes	No fire - OK
Z	30 minutes	No fire - OK

# 4.5.3.2 Altitude:

PLANE OF VIBRATION	VIBRATION CYCLE	FIRING ALTITUDE	r <b>e</b> marks
X	30 minutes at 17,000 ft.	17,400	OK
Y	30 minutes at 17,800 ft.	17,050	OK
Z	30 minutes at 17,800 ft.	17,100	OK

# 4.5.4 Remarks:

Actuator Performed Satisfactorily.

APPENDIX J SUMMARY OF TEST RESULTS

Tests		Part No.					
Number	Title	201	202	203	204	205	206
4.1	Examination of Product	F-1	-	F-1			
4.2	Venting Test	P	-	P	_		-
4.3	Aneroid Cycling			-	P	P	-
4.4	Overpressure	_		, _	P	P	_
4.5	Timer Starting Life Test	P	_	P	-	•	
4.6	Power Actuation Life Test	P		P	_	_	~
4.7.2 4.7.3	Timer Accuracy	-	P	_	P	<b>P</b> .	P
t.7.4	Aneroid Accuracy	-	P	_	P	P	F-4
+. 7. <del>4</del>	Aneroid Hysteresis		_	•••	P	P	
7. 7. J +. 8. 1	Arming Pin Pull	-	_	_	F-7	F-7	-
	High Altitude - Low Temperature	-	-		F-2	F-3	_
1.8.2	High Temperature				F_3		
1.8.3	Vibration	F-2	-		P	F-2	-
1.8.4	Shock	F-2		F-2	-		-
		F-6	-	F-2 F-6	-		
.8.4.1	Multiple Shock	1-0	P	r-0	75		
.8.5	Acceleration	P	T.	- P	P		P
.8.6	Sand and Dust	-	P	r	_	-	
.8.7	Humidity	_	F-5		-	~	
.8.8	Salt Spray	_	F-5	-	. <b>-</b>	-	-

#### Notes:

- Passed specified test procedure P F
- Failed to pass specified test procedure in the following area only
- F-1 Guide bushing for arming pin missing, otherwise passed
- F-2 Actuator firing not within applicable altitude limits F-3 Timing mechanism failed to fire within limits
- F-4 Actuator could not be cocked and was removed from testing
- F-5 Excessive corrosion was found within the actuator
- F-6 Actuator could not be cocked, was modified by Pacific Scientific
- F-7 Arming pin became prematurely disengaged

Technical Memorandum ASNP-TM-61-28

#### APPENDIX K

# TEST REQUIREMENTS FOR QUALIFICATION

#### 1.0 PURPOSE

To outline qualification procedure.

#### 2.0 REFERENCE SPECIFICATION

WADC Exhibit WCLSJ-1-23075, Appendix A, 26 November 1957, "Automatic Parachute Ripcord Release".

# 3.0 QUANTITY OF TEST ARTICLES

Five complete actuators. Each test must be performed on each actuator unless otherwise noted.

#### 4.0 TEST PROCEDURE

The tests will be conducted as follows:

# 4.1 EXAMINATION OF PRODUCT

All actuators shall be inspected to determine compliance with the referenced specification and applicable drawing.

# 4.2 VENTING TEST

With the arming pin removed, a rubber tube shall be placed over the cable guide and the other end of the tube shall be connected to an altimeter. Both the actuator and the altimeter shall be placed in an altitude chamber. The altitude shall be raised to 25,000 feet and then lowered at a rate not more than 250 fps nor less than 150 fps. The difference in the reading of the altimeter and the chamber altitude as the pressure is reduced shall not exceed 100 feet.

# 4.3 ANEROID CYCLING

The actuator shall be subjected to an aneroid accuracy test which shall be conducted prior to the start of the cycling test. With the arming pin inserted, the release shall be subjected to continuously varying altitude cycles at room temperature, from sea level to 35,000 feet and return to sea level. Upon completion of 1,000 cycles, an aneroid accuracy check shall again be made. The accuracy shall be within the requirements specified in Table I.

# 4.4 OVERPRESSURE

The actuator shall be subjected to an absolute pressure of 50 inches Hg for a period of one hour. For a period of not less than six hours following

Technical Memorandum ASNP-TM-61-28

this overpressure, the actuator shall not be subjected to any operation other than atmospheric pressure. An accuracy test shall then be made on the actuator and the accuracy shall meet the requirements specified in Table I.

#### 4.5 TIMER STARTING LIFE TEST

Three actuators shall be tested to determine the starting reliability. With the power spring <u>not</u> loaded, the timing gear train shall be started by extracting the arming pin at room temperature 300 times. The same starting operation shall be conducted an additional 200 times with the release at a temperature between  $-60^{\circ}$  and  $-65^{\circ}$ F. All three actuators must operate each time.

# 4.6 POWER ACTUATION AND LIFE TEST

The three actuators used in test 4.5 shall be loaded and operated 50 times with a resisting force of 30 pounds. The actuators shall then be mounted on a test fixture with the cable end down and a 100-pound weight attached to the terminal swaging. The actuator shall lift the 100-pound weight two (2) inches each time. These tests will be conducted at room temperature.

#### 4.7 PERFORMANCE TESTS

### 4.7.2 Timer Accuracy

When the arming pin is removed there shall be a delay of between .08 and .13 seconds at room temperature, -65°F and +165°F.

#### 4.7.3 Aneroid Accuracy

The aneroid shall be checked in an altitude chamber to determine if the aneroid accuracy is within the limits specified in Table I. The accuracy shall be checked by taking the test chamber to 18,000, 19,800 and 18,400 feet respectively for the Type 117, 118 and 119, and lowering it to determine the release point. The leak indicator shall be checked. A leak equivalent to 3,000 feet altitude must be clearly detectable.

# 4.7.4 Ameroid Hysteresis

With the fixed aneroid setting as determined in 4.7.3, the release shall be taken to 30,000 feet in an altitude chamber and then lowered at a rate of 180 to 230 fps to compare the release point obtained under these conditions with that for the 18,000, 19,800 and 18,400 feet pressure altitude settings. The tolerance shall not exceed that specified in Table I.

# 4.7.5 Arming Pin Pull

With a spring scale attached to the knob and the knob affixed to the cable housing fitting, the force required to remove the knob from the fitting shall be measured and shall be between 15 and 20 pounds. The arming pin knob shall continue to be pulled and the force required to extract the arming pin from the actuator shall be measured and shall be between 10 and 20 pounds.

#### 4.8 ENVIRONMENTAL TESTS

# 4.8.1 High Altitude - Low Temperature

The actuator shall be placed in a chamber and maintained at a temperature of approximately -65°F and a pressure equivalent to approximately 50,000 feet for a period of four hours. The actuator shall then be maintained at a temperature of approximately -65°F at atmospheric pressure for an additional period of four hours. Upon completion of the exposure and while at this temperature, the actuator shall be subjected to a timer accuracy, an aneroid accuracy, and a pull test simultaneously.

# 4.8.2 High Temperature

The actuator shall be subjected to high temperature in accordance with Procedure I of Specification MIL-E-5272, except that the actuator shall be maintained at the specified temperature for a period of 15 hours. While at this temperature, the actuator shall be subjected to a timer accuracy, an aneroid accuracy, and a pull test simultaneously.

#### 4.8.3 Vibration

The actuator, cocked and with the arming pin inserted, shall be subjected to linear vertical vibration for a period of 30 minutes in each of three mutually perpendicular planes on a suitable vibration stand. When mounted in the horizontal plane, the actuator shall be mounted upside down. In one of the positions, the actuator shall be so mounted that the pawl for the reel actuator shall have the additional force of gravity tending to trip out this pawl. During this period of vibration, the frequency shall be varied continuously from 10 to 55 cps with a double amplitude (total .excursion) of 0.030 inch. The actuator shall not operate the ripcord power cable during the period of vibration. The actuator shall then be placed in an altitude chamber and subjected to a pressure corresponding to 19,000, 16,500 and 15,000 feet respectively. The actuator shall be vibrated for at least 30 minutes in each plane. Upon completion of the vibration in each plane, the arming pin shall be pulled and the altitude brought up or down as applicable to ascertain the altitude at which the actuator operates. After the vibration tests, the actuator shall undergo the tests specified in paragraph 4.7 noting particularly whether the timer runs down without operating the ripcord. No looseness in the mechanism nor damage to any part of the actuator shall result from this test.

#### 4.8.4 Shock

The actuator shall be mounted on sufficient mass and dropped from such a height that when decelerated by resiliant impact a deceleration of 30 g shall be obtained. The actuator cocked and with the arming pin inserted shall be tested with the axis mounted in three different planes. The actuator shall not pull the power cable during these tests. The actuator shall be mounted in a horizontal plane with a mounting side of the timer down on a shock testing machine in an altitude chamber. At an altitude of 1,000 feet above the elevation at which the actuator should theoretically trip, the arming pin shall be removed. While still at this altitude, the actuator shall be subjected to a 30 g shock and shall not trip the power cable. The test shall be repeated with the timer turned over 180° for a 30 g shock under the same conditions. The actuator shall then be subjected to a shock of 30 g in each of two additional planes at right angles to the first plane and at right angles to each other. The device shall be shocked under the same conditions in two different positions reversed to each other for each plane or a total of six different positions in all. A mechanism conforming to Specification JAN-S-44 may be used for conducting these tests, except that the calibrated spring shall have a constant (K) of 1,590  $\pm$  100 pounds per inch in lieu of a spring rate of 5,000-5,500 pounds per inch. After the shock test, the actuator shall undergo the tests specified in paragraph 4.7. No looseness in the mechanism nor damage to any part of the actuator shall result from this test.

### 4.8.4.1 Multiple Shock

Three actuators attached to a mounting plate as for service shall be placed in an altitude chamber and taken 1,000 feet above basic setting of release #2. The arming pins shall be pulled on all three actuators. Firing of actuator #1 shall not cause actuators #2 and #3 to fire. While still at this altitude, the mounting plate with the releases installed shall be subjected to a 30 g shock. The shock will not cause actuators #2 and #3 to fire. The chamber altitude shall be reduced to determine the release point of actuators #2 and #3. The actuators shall be shocked in six different positions at room temperature (reference paragraph 4.8.4) in accordance with the procedures described above.

# 4.8.5 Acceleration

The actuator shall be mounted on the apparatus (centrifuge) and the apparatus shall be operated at a speed that will produce 30 g. The actuator shall be mounted first in a position parallel to the escapement assembly (usually horizontal) on the center of the turntable which is secured to the mounting platform of the centrifuge. The applied acceleration of 30 g shall be attained, stabilized, and maintained for a period of not less than one minute for each successive position. At the end of the one minute period, the arming pin shall be pulled. The actuator shall operate under these conditions and the apparatus (centrifuge) slowed.

The actuator shall then be checked and reset for the next test. The release shall be subjected to tests where the release is mounted in positions that will allow a 30 g force to be applied in the plus or mimus direction along the x, y and z axes and the actuator set in six different positions for these axes. The actuator shall operate satisfactorily on all tests.

# 4.8.6 Sand and Dust

The actuator mounted in a parachute pack, or equivalent, shall be subjected to the sand and dust tests in accordance with Procedure I of Specification MIL-E-5272. The actuator shall then be subjected to the tests specified in paragraph 4.7. There shall be no evidence of sand or dust within the actuator.

#### 4.8.7 Humidity

The actuator mounted in a parachute pack, or reasonable engineering facsimile, shall be subjected to humidity tests in accordance with Procedure I of Specification MIL-E-5272, for five cycles. At the completion of the test, the release shall be inspected for collection of moisture in the interior of the case, corrosion of metal parts, or other damage. At the completion of the fifth cycle, the actuator shall undergo the tests specified in paragraph 4.7.

#### 4.8.8 Salt Spray

The actuator mounted in parachute pack, or reasonable engineering facsimile, shall be subjected to a salt spray in accordance with Procedure I of Specification MIL-E-5272 for a period of 50 hours. At the end of this period, the actuator shall undergo the tests specified in paragraph 4.7.

TABLE I
PRESSURE ALTITUDES

Pressure altitudes <u>below</u> which timer is blocked	Tole	t	
	-65°F	Temp.	+160° <b>F</b>
1201117-0 19,000 ft.	±1000	±500	±1000
Pressure altitude above which timer is blocked			
1201118-0 16,500 ft.			
1201119-0 15,000 ft.			

QUALIFICATION TESTING OF THE
PACIFIC SCIENTIFIC COMPANY'S
ALTITUDE SENSITIVE ACTUATORS, NOS.
1201117-0, 1201118-0 & 1201119-0